

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	44	(plane planar) with (marker fiducial) and 382/106,154.cccls:	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/30 20:27
L2	5523	(orient\$5 rotation rotating rotate) near4 (fiducial marker)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/30 20:38
L3	957	(orient\$5 rotation rotating rotate) near4 (fiducial marker) and (pose (three near2 dimension) "3D")	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/30 20:38
L4	585	(orient\$5 rotation rotating rotate) near2 (fiducial marker) and (pose (three near2 dimension) "3D")	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/30 20:39
L5	425	(orient\$5 rotation rotating rotate) near2 (fiducial marker) and (pose (three near2 dimension) "3D") and image	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/30 20:39
L6	130	(orient\$5 rotation rotating rotate) near2 (fiducial marker) and "382"/\$.cccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/30 20:50
L7	8	(orient\$5 rotation rotating rotate) near2 (fiducial marker) and 382/154.cccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/30 20:55
L8	111	(shape near2 shape) and 382/154.cccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/30 20:56

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L9	387	(shape near2 object) and 382/154.ccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/30 20:56
L10	641	determin\$5 near 2(shape near2 object) and 382/154.ccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/30 20:56
L11	48	determin\$5 near2 (shape near2 object) and 382/154.ccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/30 22:29
L12	2	"6101455".pn.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/30 22:29
L13	28	("4238828" "4412121" "4639878" "4645348" "4672562" "4675502" "4753569" "4942539" "4979815" "5321353" "5329469" "5513276" "5666202").PN. OR ("6101455").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2007/01/30 22:29
S1	1544	382/154.ccls. and (fiducial point marker)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/26 22:50
S2	245	382/154.ccls. and (fiducial marker)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/26 23:00
S3	245	382/154.ccls. and (fiducial marker)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/28 19:09
S4	2	"20030137510".pn.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/28 19:08

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S5	13	liew.xa.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/28 19:09
S6	6	382/154.ccls. and kosaka.inv.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/28 20:56
S7	391	pose near estimation	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/28 21:12
S8	0	"10603135".ap.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/28 21:14
S9	2	"20040258306".pn.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/28 21:14
S10	318	382/154.ccls. and (((position location) and (orientation)) pose) with object	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/29 14:38
S11	344	382/106,154.ccls. and (((position location) and (orientation)) pose) with object	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/29 14:38
S12	216	382/106,154.ccls. and (((position location) and (orientation)) pose) near3 object	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/29 14:38
S13	181	382/106,154.ccls. and (((position location) and (orientation)) pose) near3 object and plane	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/29 14:39

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S14	185	382/106,154.ccls. and (((position location) and (orientation)) pose) near3 object and (plane planar)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/29 14:39
S15	185	382/106,154.ccls. and (((position location) and (orientation)) pose) near3 object and (plane planar)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/29 21:43
S16	2	"20040258306".pn.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/29 19:39
S17	125	382/106,154.ccls. and (((position location) and (orientation)) pose) with object and (plane planar) with (normal perpendicular vector)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/29 22:33
S18	7	382/106,154.ccls. and (determin\$4 calculat\$4) with (normal vector) with (fiducial marker mark)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/29 22:12
S19	2798	(determin\$4 calculat\$4) with (normal vector) with (fiducial marker mark)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/29 22:13
S20	29	(determin\$4 calculat\$4) with (normal vector) with (fiducial marker mark) with (pose (orientation and (location position)))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/29 22:21
S21	4264	(determin\$4 calculat\$4) with (normal vector) with (pose (orientation and (location position))) fiducial marker mark	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/29 22:26
S22	2928	(determin\$4 calculat\$4) with (normal vector) with (pose fiducial marker mark)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/29 22:22

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S23	1419	(determin\$4 calculat\$4) with (normal) with (pose fiducial marker mark)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/29 22:25
S24	109	(determin\$4 calculat\$4) near3 (normal) near3 (pose fiducial marker mark)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/29 22:22
S25	643	(determin\$4 calculat\$4) with (normal) with (pose fiducial marker mark) and image	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/29 22:25
S26	34	(determin\$4 calculat\$4) with (normal) with (pose fiducial) and image	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/29 22:25
S27	59	(determin\$4 calculat\$4) with (normal near vector) with (pose (orientation and (location position)) fiducial marker mark)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/29 22:27
S28	52	(determin\$4 calculat\$4) with (normal near vector) with (pose (orientation and (location position)) fiducial marker)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/29 22:27
S29	24	382/106,154.ccls. and (normal near vector) and (marker fiducial)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/29 23:04
S30	7	(calculat\$6 determin\$6) with (normal near vector) same (marker fiducial)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/29 23:07
S31	195	(calculat\$6 determin\$6) with (normal near vector) and (marker fiducial)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/29 23:12

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S32	895	(calculat\$6 determin\$6) with (normal) with (marker fiducial)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/29 23:13
S33	30	(normal near2 vector) with (marker fiducial)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/30 12:25
S34	4571	(plane plnar) with (marker fiducial)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/30 12:25
S35	5450	(plane planar) with (marker fiducial)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/30 12:25
S36	320	coordinate with (plane planar) with (marker fiducial)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/30 12:26
S37	492	(plane planar) with (marker fiducial) and (((three near dimensional) "3D" 3D) near3 image)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/30 12:27
S38	239	(plane planar) near3 (marker fiducial) and (((three near dimensional) "3D" 3D) near3 image)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/30 12:29
S39	16	(plane planar) near3 (marker fiducial) and 382/106,154.ccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/30 12:29
S40	44	(plane planar) with (marker fiducial) and 382/106,154.ccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2007/01/30 12:29